



ParticleSfM: Exploiting Dense Point Trajectories for Localizing Moving Cameras in the Wild

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Wang Zhao, Shaohui Liu, Hengkai Guo, Wenping Wang, Yong-Jin Liu



ETH zürich

 ByteDance



RGB video → Dense 3d geometry and camera poses



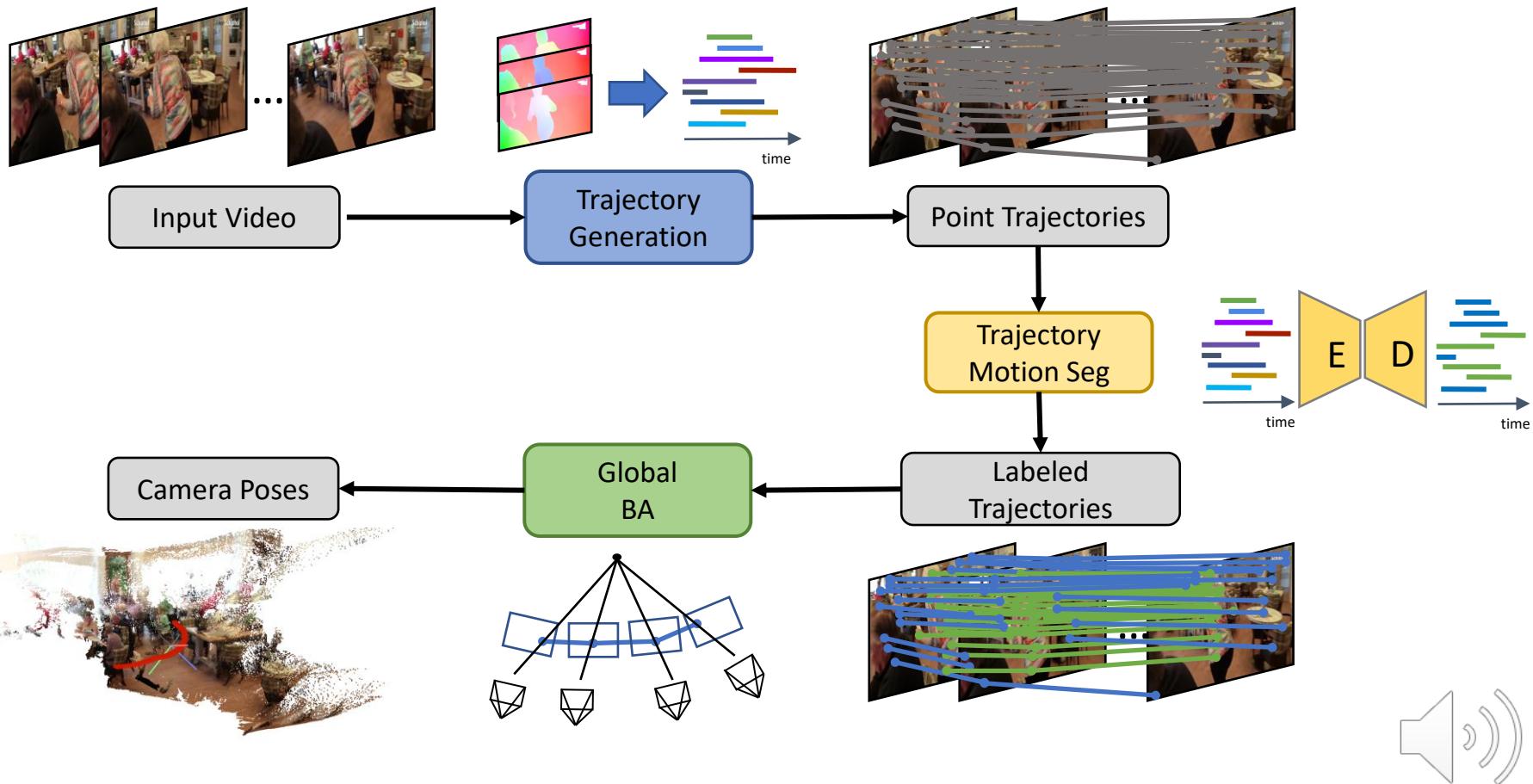
RGB video → Dense 3d geometry and camera poses



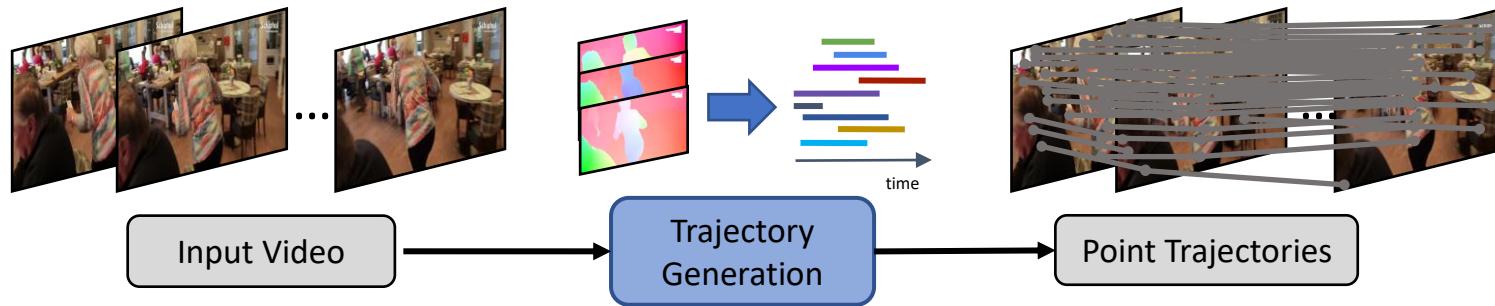
Top: COLMAP

Bottom: Ours

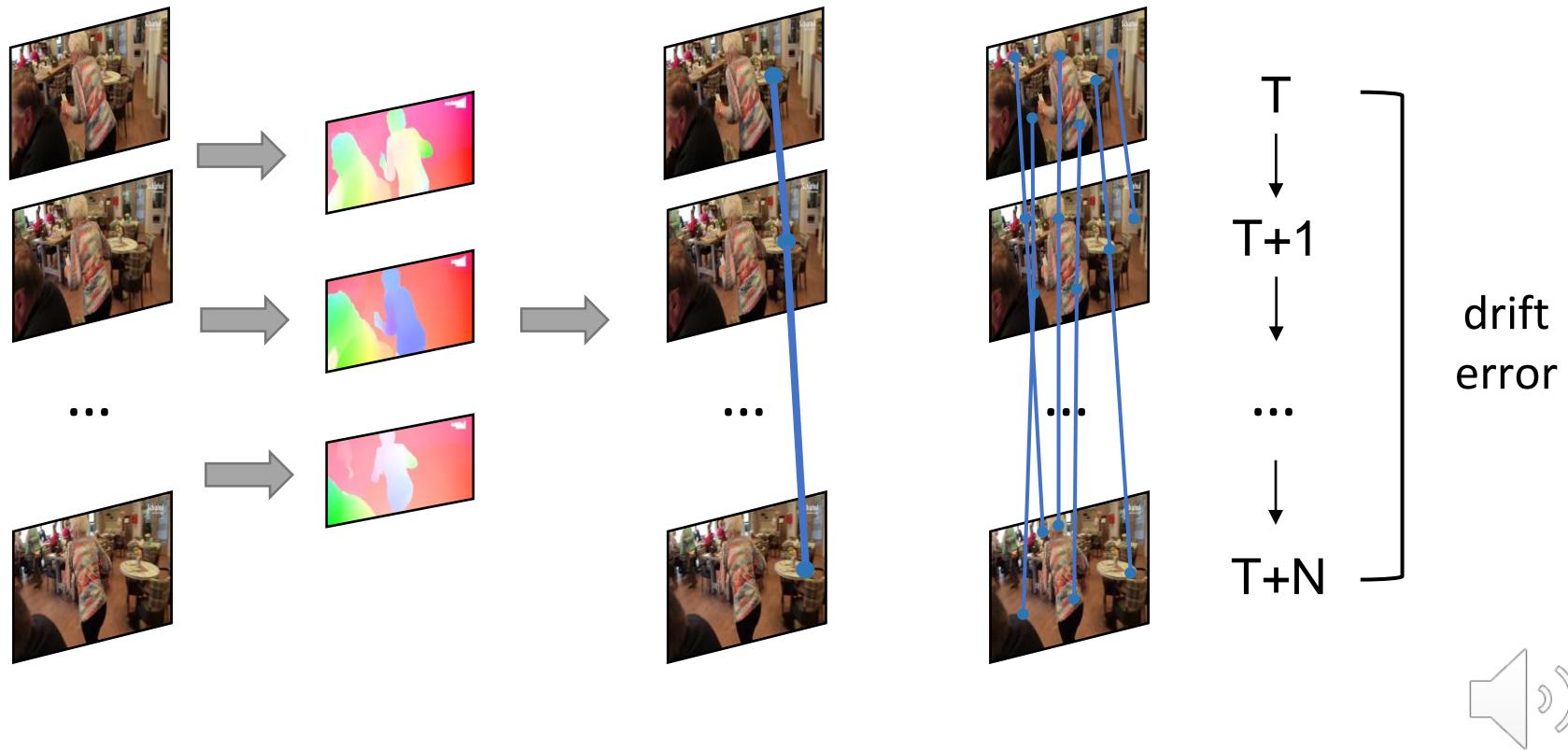




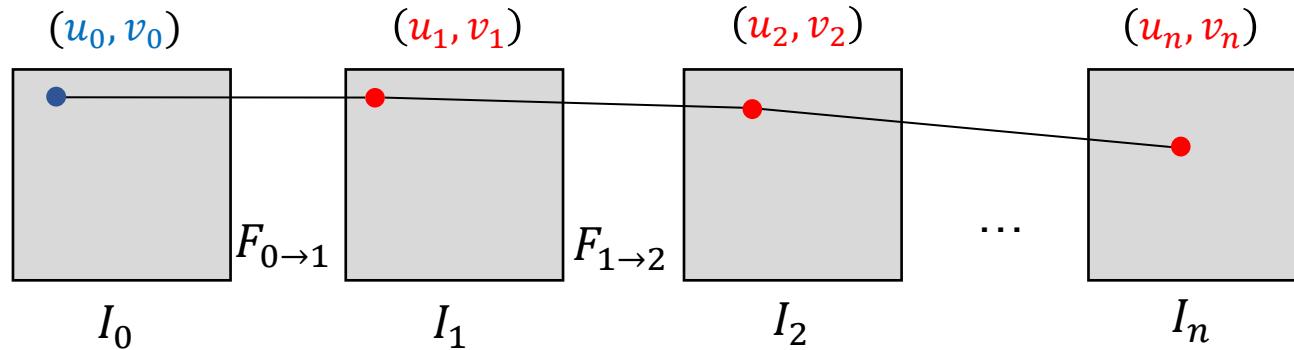
Trajectory Generation



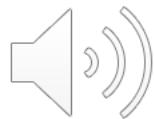
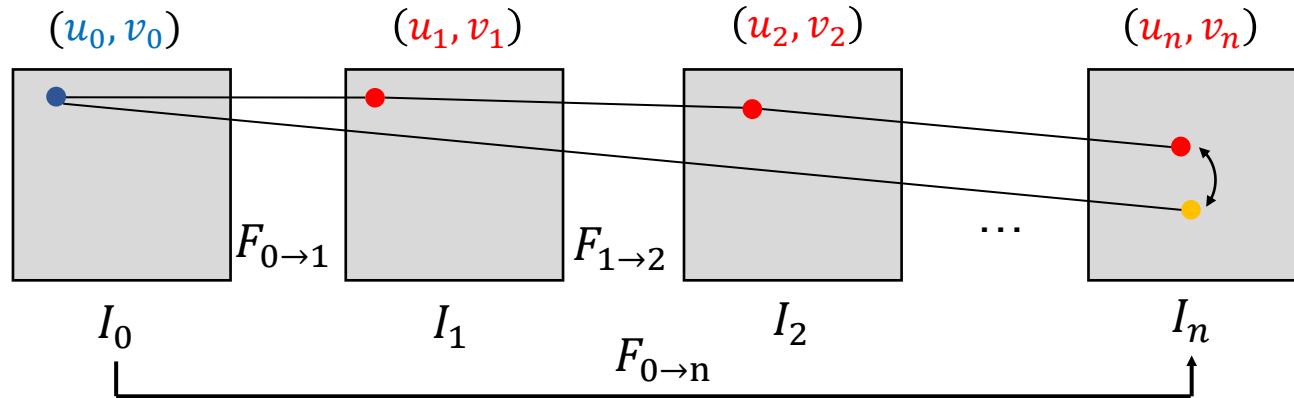
Trajectory Generation



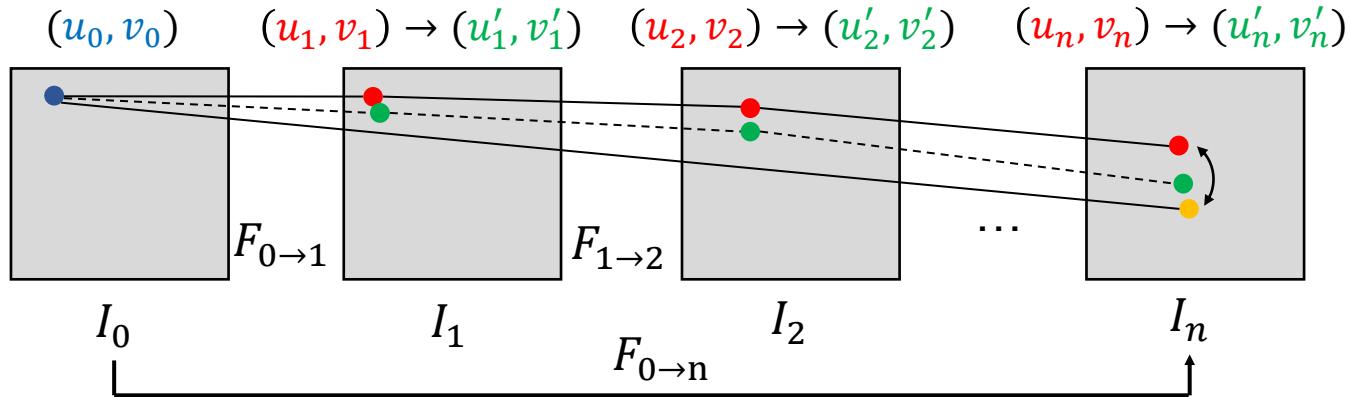
Trajectory Generation



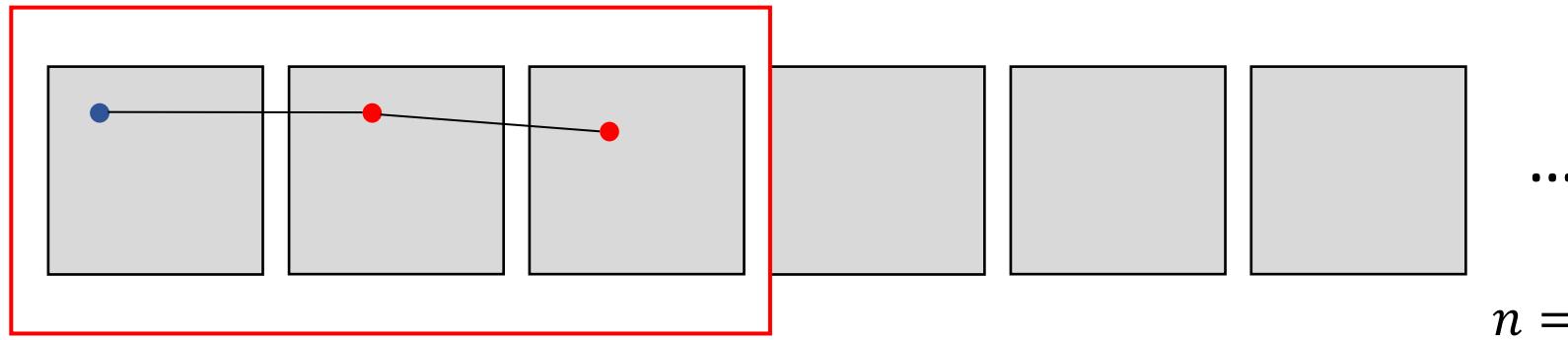
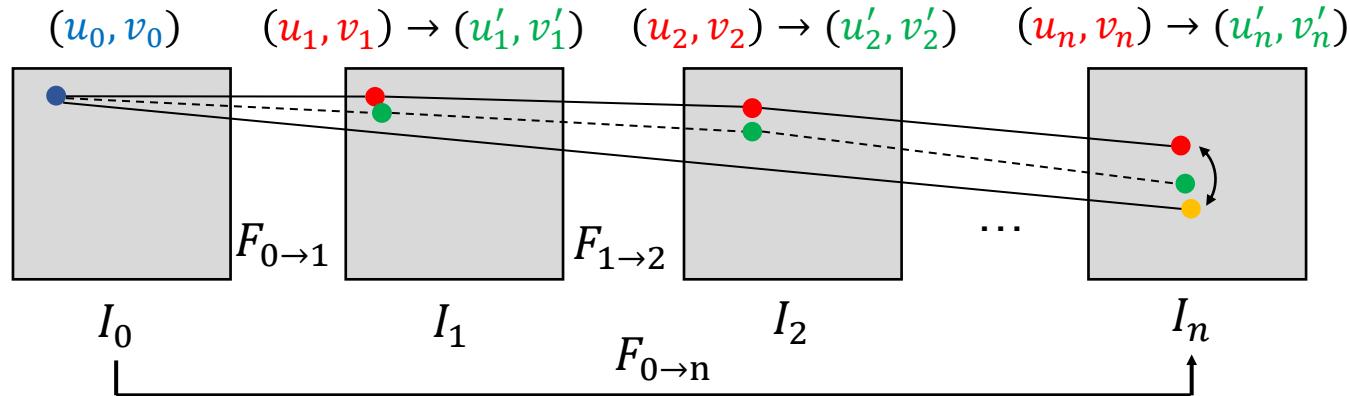
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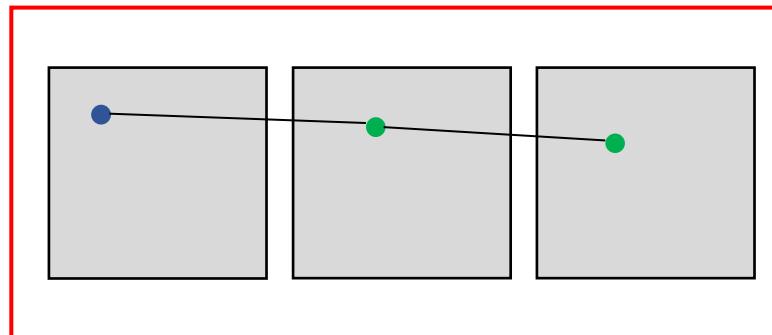
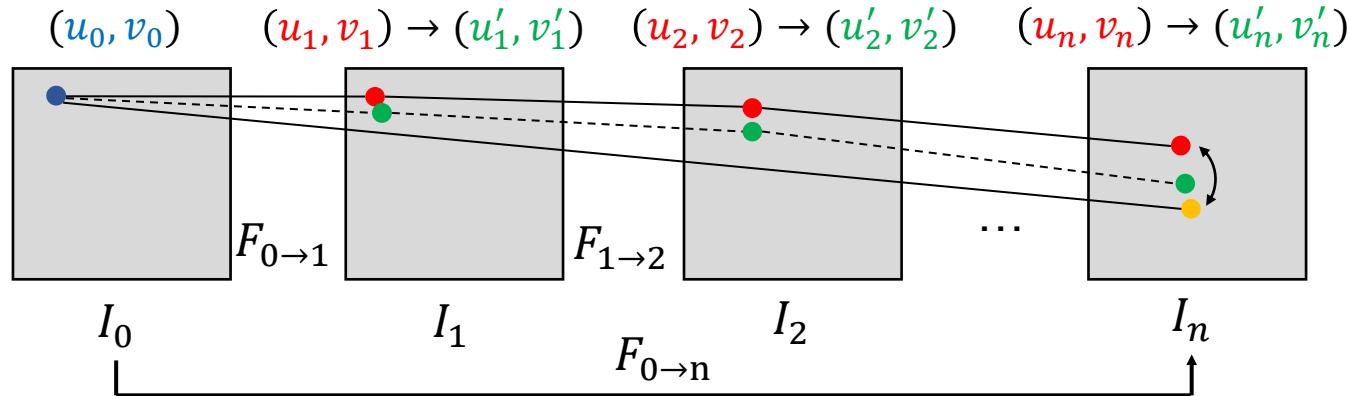
Trajectory Generation



Trajectory Generation

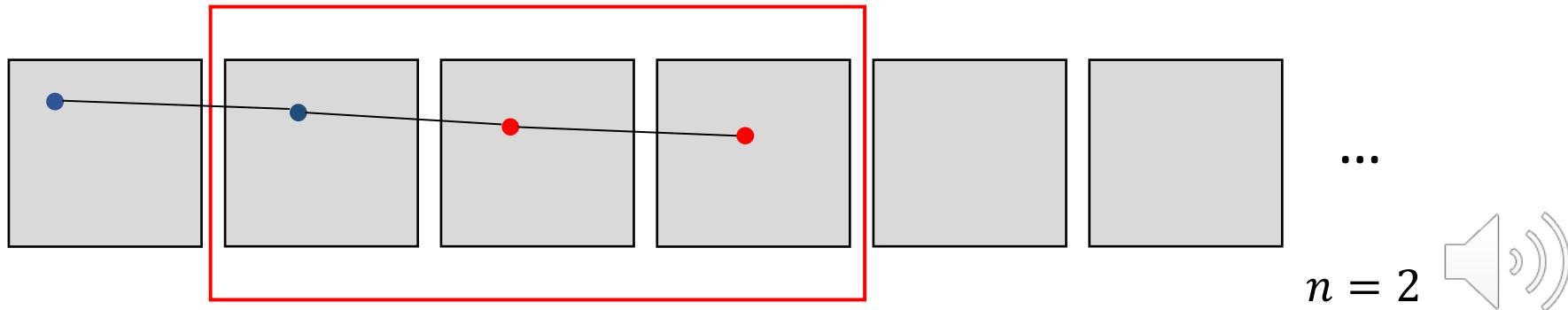
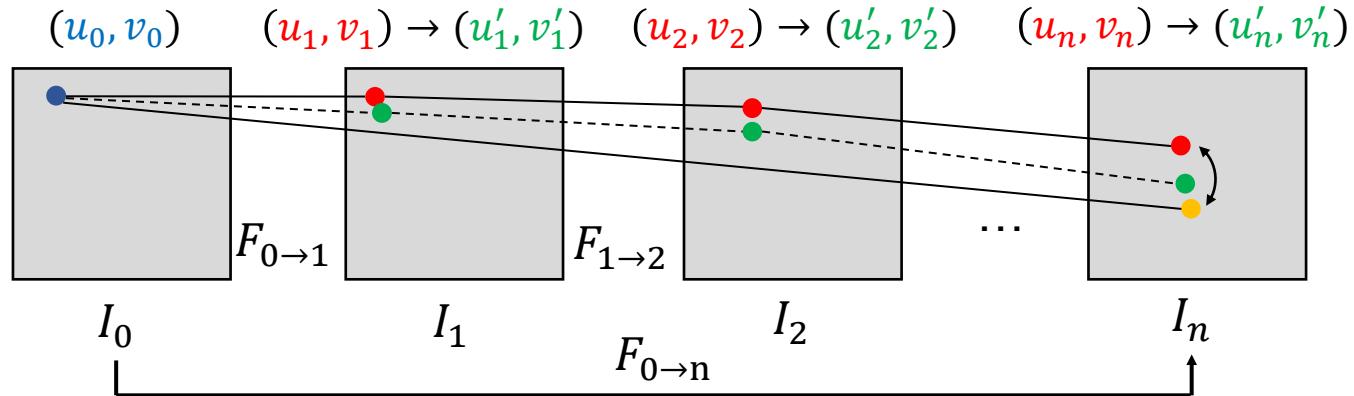


Trajectory Generation

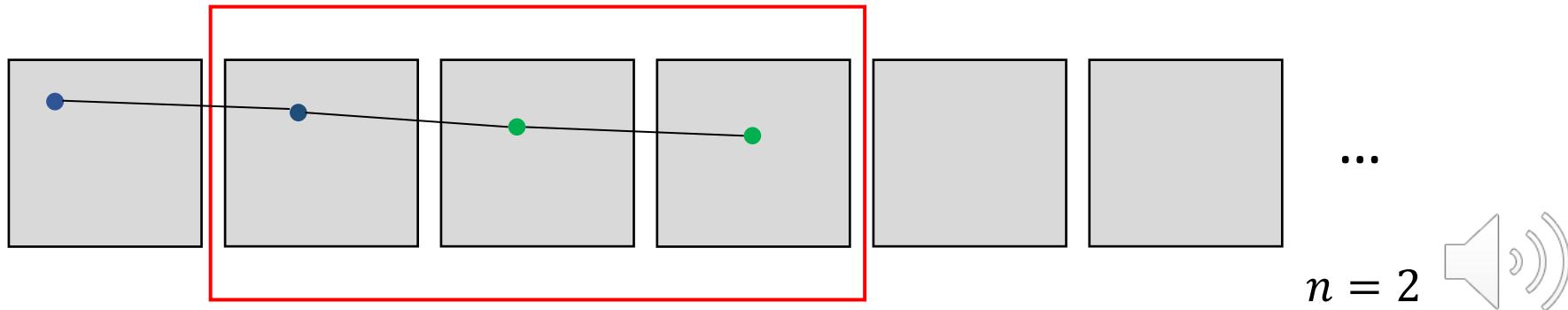
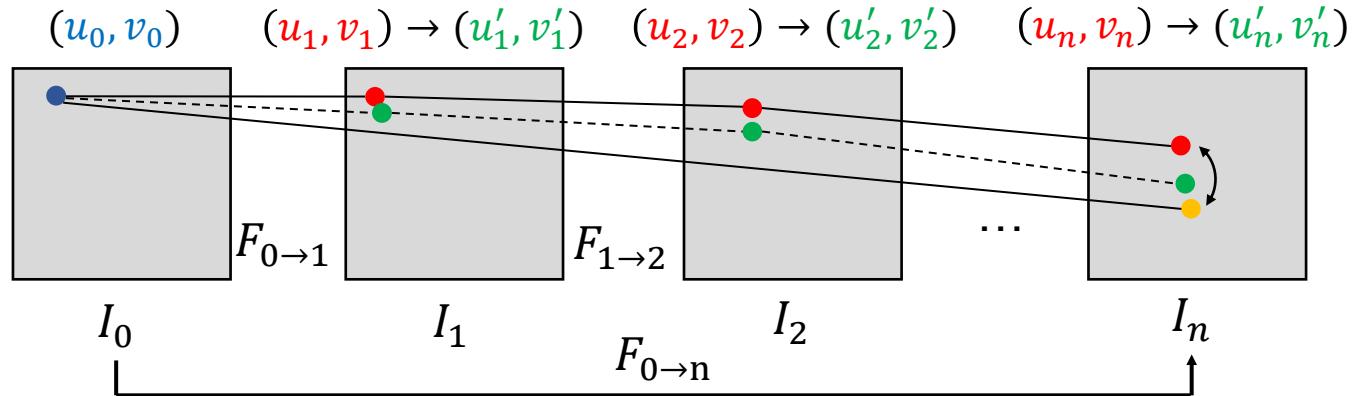


$n = 2$

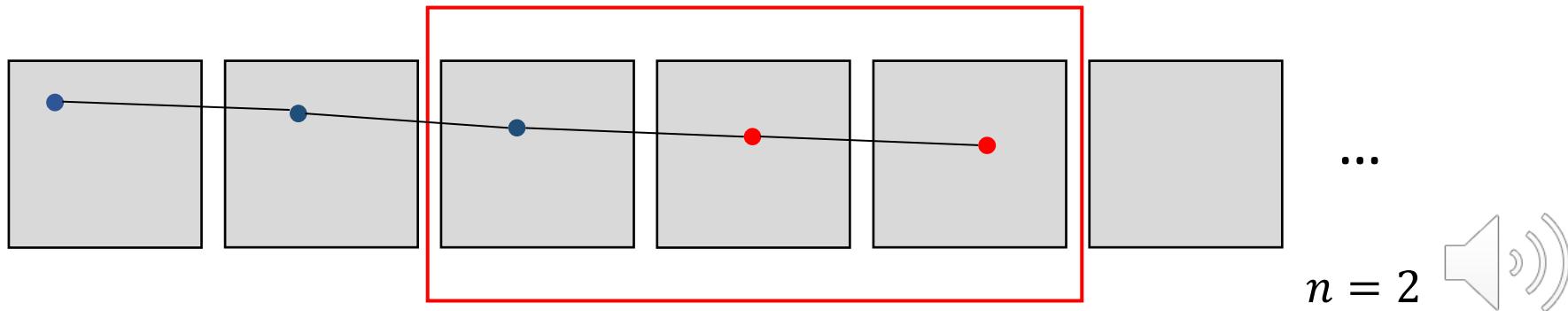
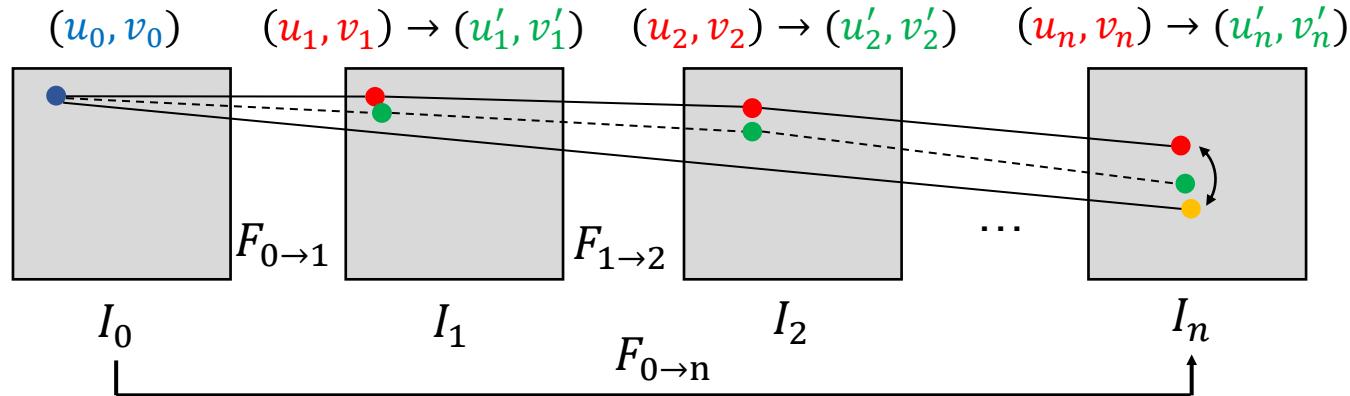
Trajectory Generation

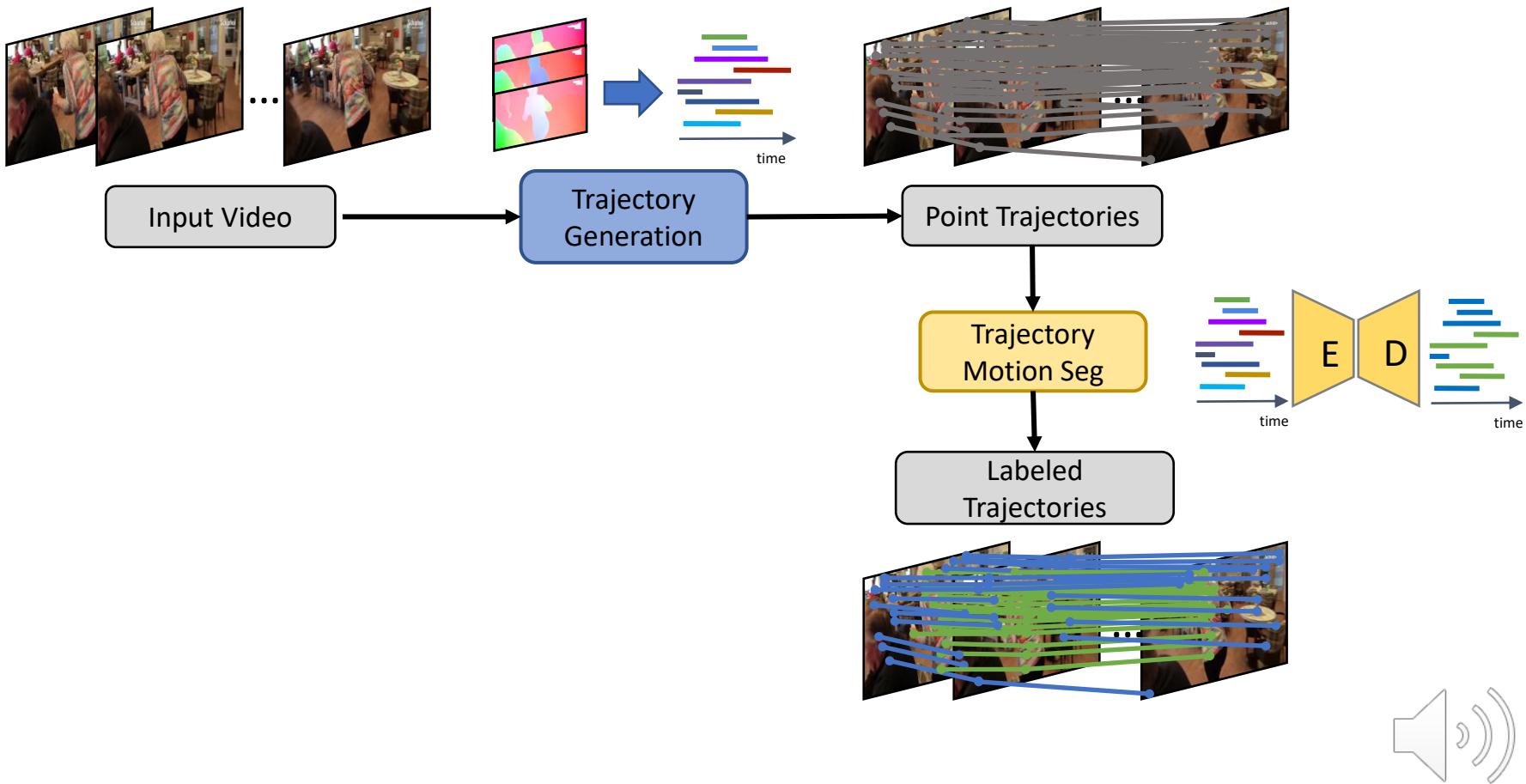


Trajectory Generation



Trajectory Generation

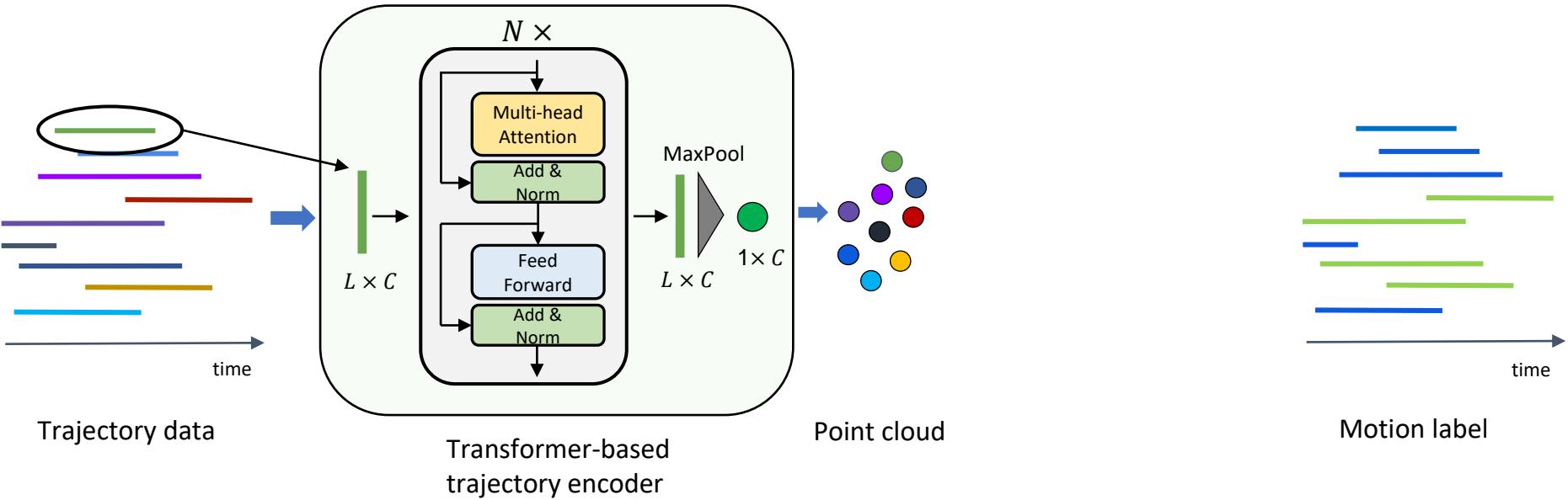




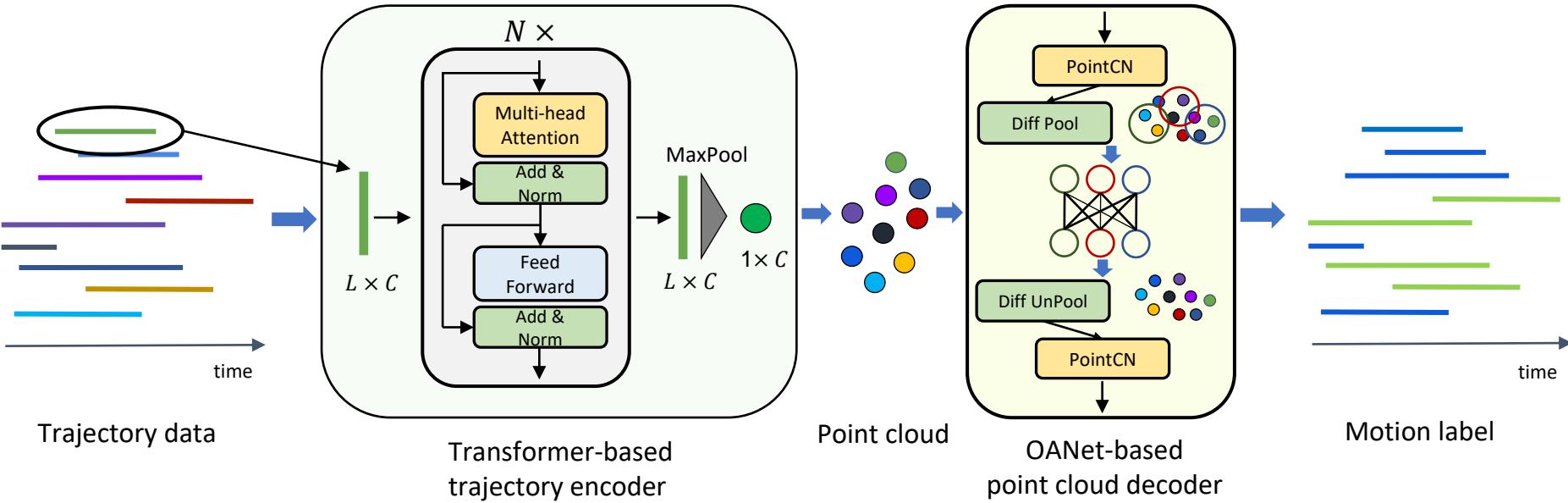
Trajectory-based Motion Segmentation



Trajectory-based Motion Segmentation



Trajectory-based Motion Segmentation



Trajectory-based Motion Segmentation



Trained only on synthetic Flyingthings3D dataset and generalize to the open world

Trajectory-based Motion Segmentation

Sample frame



Mask RCNN



MAT

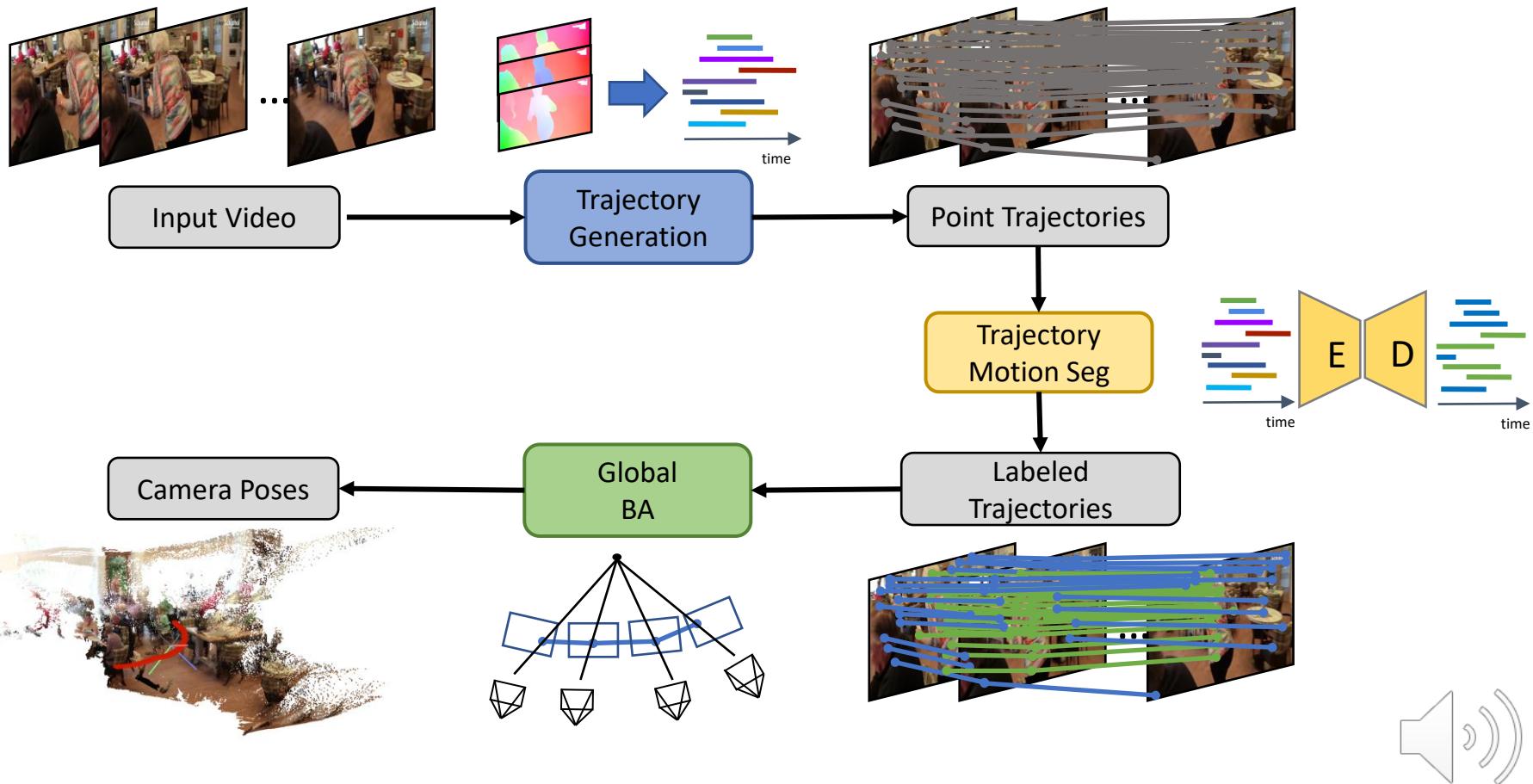


Ours

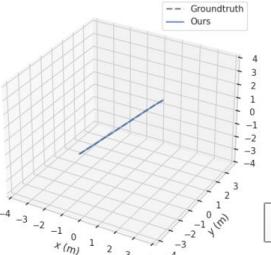
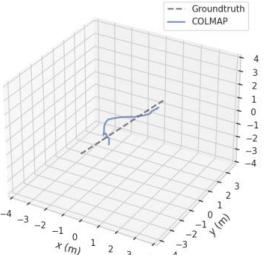
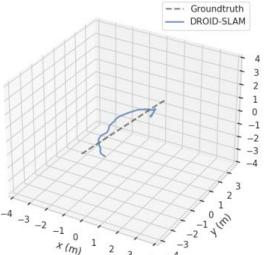
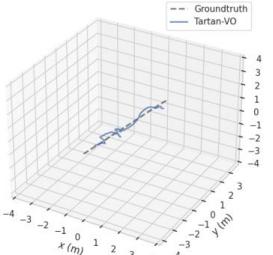
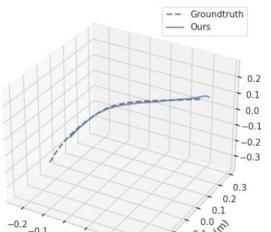
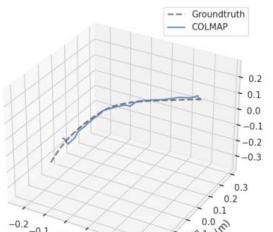
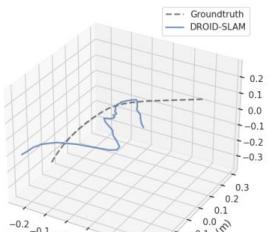
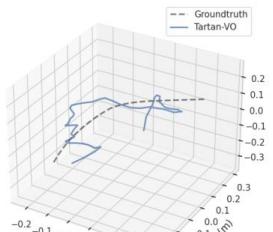
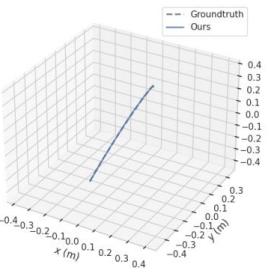
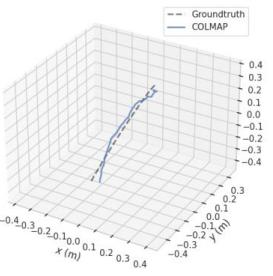
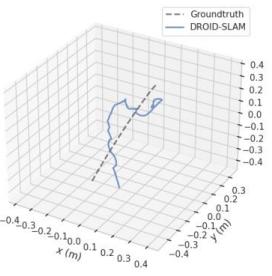
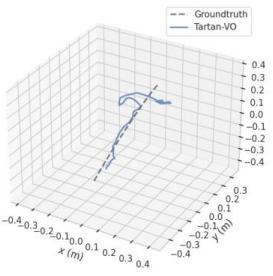


He et al., Mask R-CNN, ICCV 2017

Zhou et al., Motion-attentive Transition for Zero-shot Video Object Segmentation, AAAI 2020



Evaluation – Sintel dataset



Sample frames

Tartan-VO

DROID-SLAM

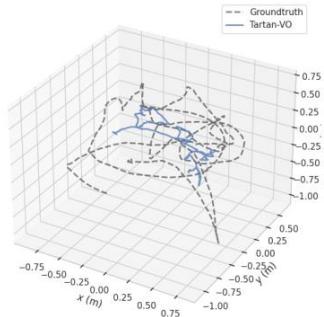
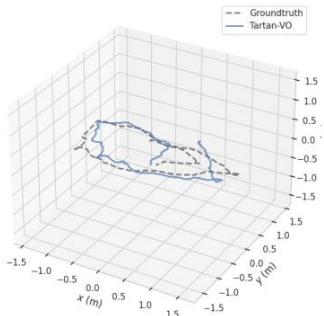
COLMAP

Ours

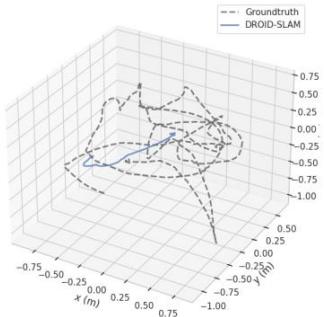
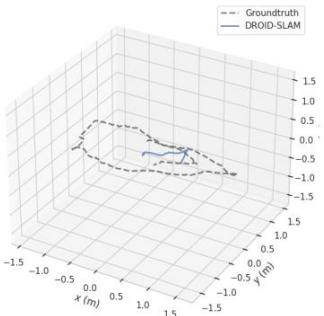
Evaluation – ScanNet dataset



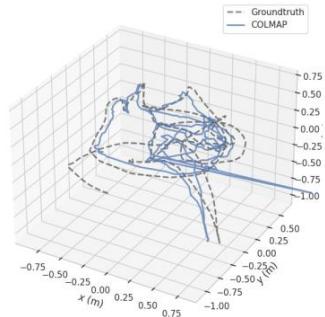
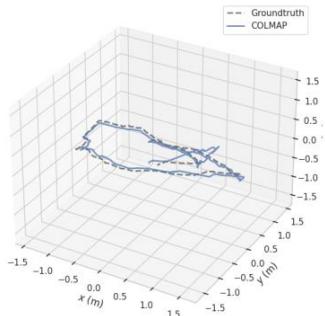
Sample frames



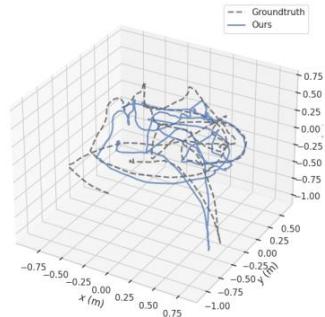
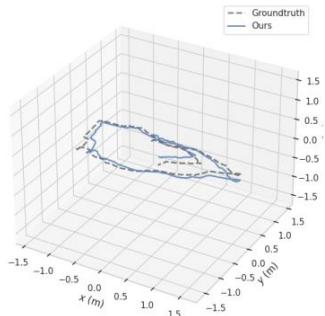
Tartan-VO



DROID-SLAM

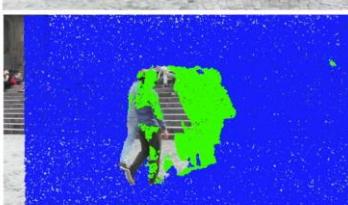
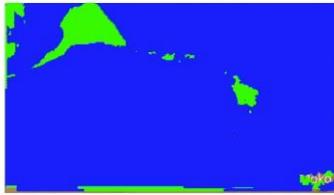
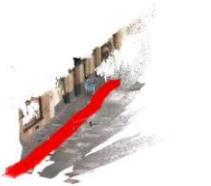


COLMAP



Ours

Evaluation – In-the-wild sequences





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Code and more results at

<http://b1ueber2y.me/projects/ParticleSfM>

